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$r = \sqrt{a^2 + R^2 - 2aR \cos(\theta - \phi)}$ , where  $\theta$  and  $\phi$  are the polar angles in x and y space, respectively. Second, our solution must be valid for all y in the circle; hence the distance of y from the origin must now become a variable, which we shall call r. Finally, note that  $\mathbf{ds} = R d\theta \mathbf{e}_\theta$ , so we can write the solution in polar coordinates as

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The position vector,  $\mathbf{r}$ , is defined as the vector that points from the origin to the point (x,y,z), and is used to locate a specific point in space. It can be written in terms of the standard unit vectors as  $\mathbf{r} = x\mathbf{i} + y\mathbf{j} + z\mathbf{k}$ . A displacement vector is the difference between two position vectors. For position vectors  $\mathbf{r}_1$  and  $\mathbf{r}_2$ ,

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On the other hand  $a = 14$  and  $b = 6$ , so the triangle inequality asserts that  $a \leq 14 + 6$ . The numbers bear this out:  $14 \leq 3.74$ , while  $14 + 6 \leq 1.41 + 2.45 = 3.86$ . (b) We find that  $\mathbf{u} \cdot \mathbf{v} = (\mathbf{u} \cdot \mathbf{w}) + (\mathbf{w} \cdot \mathbf{v})$ , so the result follows from the triangle inequality with  $a$  replaced by  $\mathbf{u} \cdot \mathbf{w}$  and  $b$  replaced by  $\mathbf{w} \cdot \mathbf{v}$ .

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that we multiply each component of the vector by the scalar. In symbols this means that:  $a + b = (a_1, a_2, \dots, a_n) + (b_1, b_2, \dots, b_n) = (a_1 + b_1, a_2 + b_2, \dots, a_n + b_n)$  and  $ka = (ka_1, ka_2, \dots, ka_n)$ . In our particular examples,  $(1, 2, 3, 4) + (5, 1, 2, 0) = (6, 3, 5, 4)$ , and  $2(7, 6, 3, 1) = (14, 12, 6, 2)$ .

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