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systems (open-
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*Discrete control
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10: Continuous-
time models of

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discrete-time
systems State
Space, Part 1:
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A real control
system - how to
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Alstom Grid DS
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Stable System
Why Z
System Philips
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transforms? For
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control systems
DCS -unit2 LEC
-1 Stability
Analysis of
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Machine for
liquid and
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*Hardware Demo of
a Digital PID
Controller
Liquid Filling
Machine*

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Instructions ok

070583 What is

DIRECT DIGITAL

CONTROL? What

does DIRECT

DIGITAL CONTROL

mean? **Intro to**

Control - 2.1

Modeling R, L,

and C in the

Frequency Domain

Digital control

23: The digital

root locus, Part

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1 An explanation of the Z transform part 1

Digital Control
- Stability

Methods - Jury's
Test *What is a
PID Controller?*

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Example fully
explained with
complete process
in Control
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control #2:
Discretize!
Going from
continuous to
discrete domain

~~GATE 2018~~

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~~Questions~~

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4: Z-transform

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Manual Solution:

$$x(k+1) = Ax(k); \quad x(k) = A^k x(0)$$
$$x(k+1) = A^k x(0)$$

Since this is true for any $x(0)$, $x(k+1) = A^k x(0)$

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calculations and allows him to consider more subtle aspects of control system analysis and design. An engineering approach to digital controls: emphasis throughout the book is on

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design of control systems. Mathematics is used to help explain concepts, but throughout the text discussion is tied to design and implementation. For example coverage of analog controls

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in chapter 5 is not simply a review, but is used to show how analog control systems map to digital control systems Review of Background Material:

contains review material to aid understanding of digital control

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analysis and design. Examples include

discussion of discrete-time systems in time domain and frequency domain (reviewed from linear systems course) and root locus design in s -domain and z -domain (reviewed

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from feedback
control course)
Inclusion of
Advanced Topics

In addition to
the basic topics
required for a
one semester
senior/graduate
class, the text
includes some
advanced
material to make
it suitable for

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an introductory graduate level class or for two quarters at the senior/graduate level. Examples of optional topics are state-space methods, which may receive brief coverage in a one semester course, and

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nonlinear
discrete-time
systems Minimal
Mathematics

Prerequisites

The mathematics
background
required for
understanding
most of the book
is based on what
can be
reasonably
expected from

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the average
electrical,
chemical or
mechanical

engineering
senior. This
background
includes three
semesters of
calculus,
differential
equations and
basic linear
algebra. Some

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texts on digital
control require
more

This text's
contemporary
approach focuses
on the concepts
of linear
control systems,
rather than
computational

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mechanics.
Straightforward
coverage
includes an
integrated
treatment of
both classical
and modern
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methods. The
text emphasizes
design with
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formulation,
design criteria,
physical
constraints,
several design
methods, and
implementation
of compensators.
Discussions of
topics not found
in other
texts—such as
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and robust tracking—add to the text's cutting-edge presentation. Students will appreciate the applications and discussions of practical aspects, including the leading problem in developing

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block diagrams,
noise,
disturbances,
and plant

perturbations.

State feedback

and state

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state variable

equations and

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comparison of
the two
approaches. The
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throughout the
text helps
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design and

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A comprehensive treatment of the analysis and design of discrete-time control systems which provides a gradual development of the theory by

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