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(a) We know that $y_i[n] = x[n] * h[n] = \sum_{k=-\infty}^{\infty} h[k]x[n-k]$ (S2.1-1) The signals $x[n]$ and $h[n]$ are as shown in Figure S2.1.

Figure S2.1 From this figure, we can easily see that the above convolution sum reduces to $y_i[n] = h[-1]x[n+1] + h[1]x[n-1]$...

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$x_2(t) = Ay_1(t) + By_2(t)$ where $y_i(t)$, $i=1;2$, are the corresponding outputs to $x_i(t)$, $i=1;2$. ii. If $x(t) = u(t)$ then $y(t) = r(t)$ and if $x_1(t) = u(t)$ the corresponding output is $y_1(t) = y(t)$. System is time-invariant. In general, if $x_1(t) = x(t)$ the output is $y_1(t) = y(t)$.

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